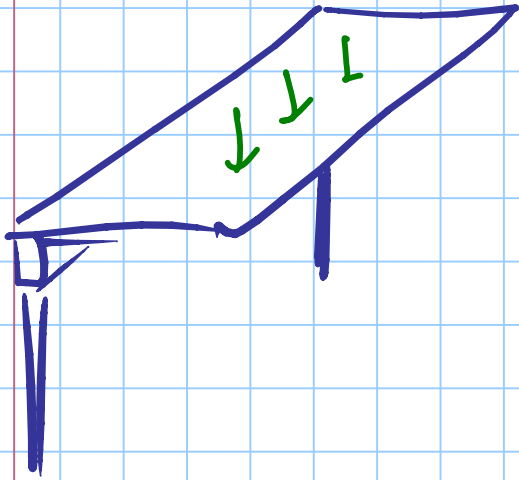


TORSIONE

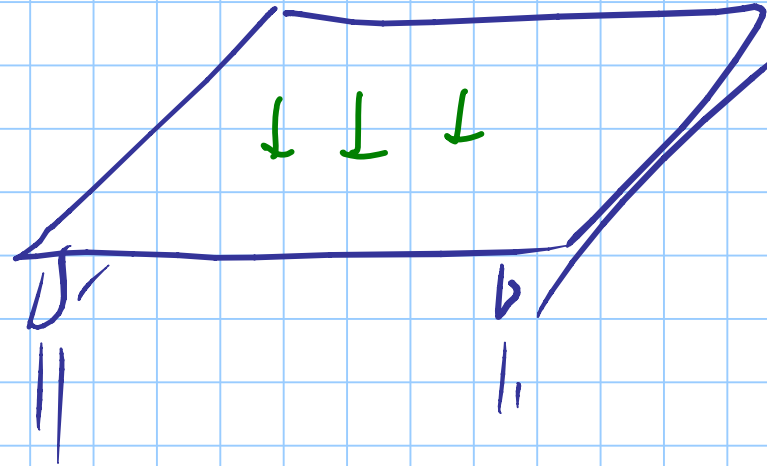
Titolo nota

17/12/2013

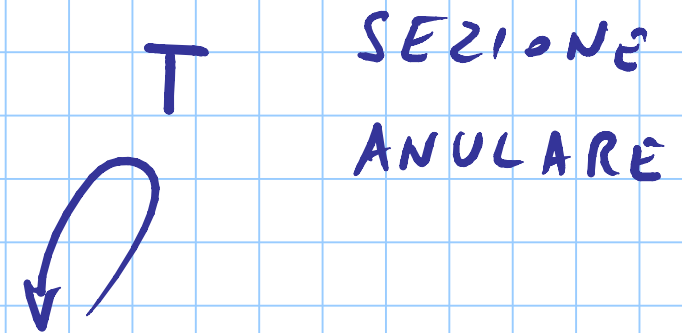
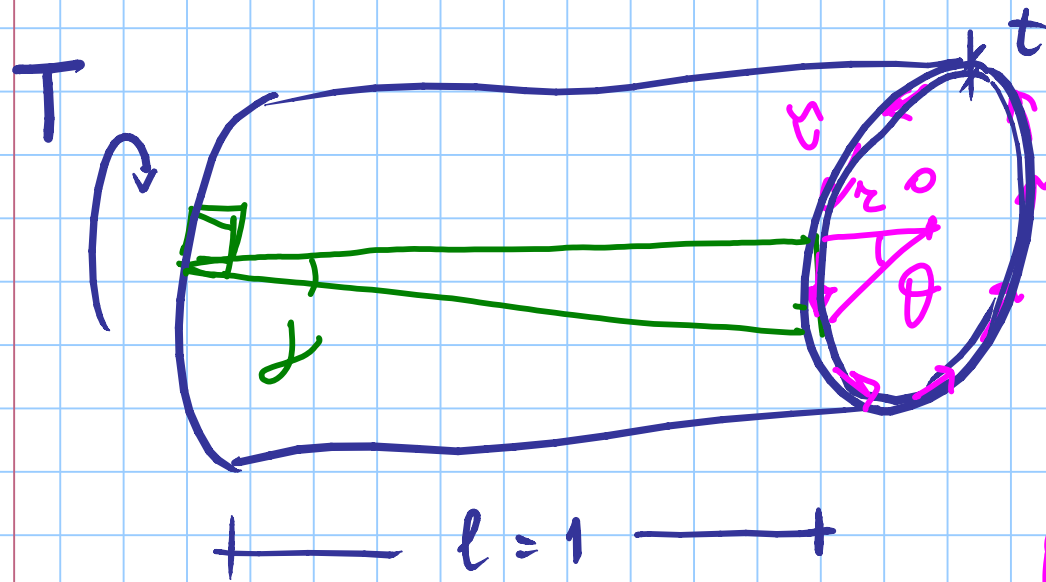
per equilibrio.



per congruenza



si può torsionare



θ angolo di rotazione unitaria

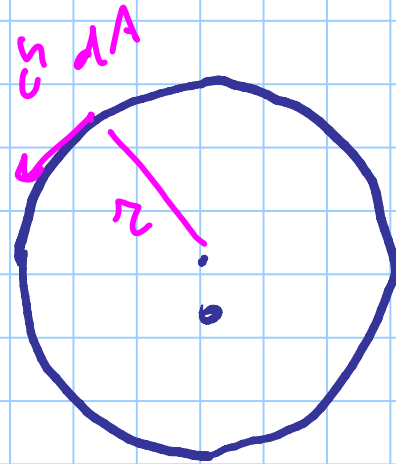
$$\gamma = G \gamma$$

$$1 \cdot \gamma = r \theta$$

$$\gamma = G r \theta$$

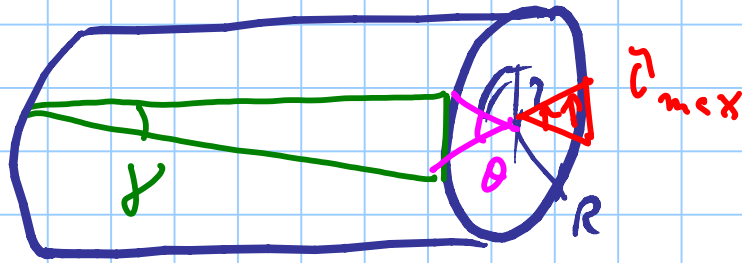
$$T = \int \rho \, dA \, r^2 =$$

$$= \frac{\rho}{r^2} \int r^2 \, dA = \frac{\rho I_p}{r^2}$$



$$I_p \text{ (or } I_t)$$

momento d'inerzia polare



SEZIONE
CIRCOLARE
PIENA

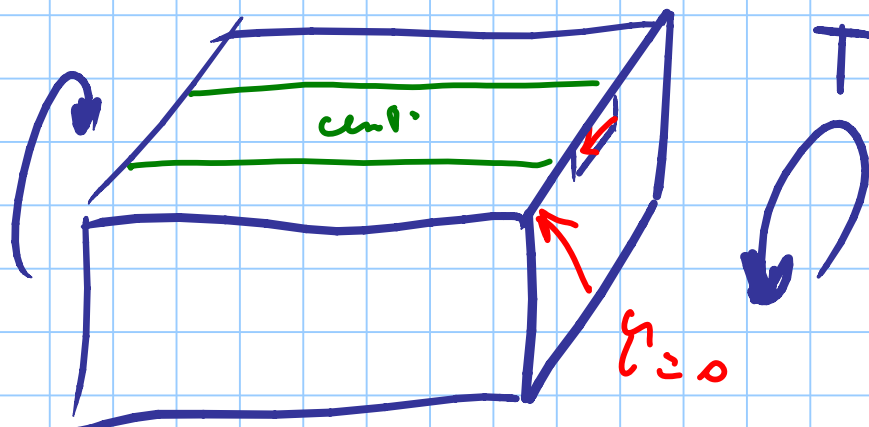
$$\tau = \tau_{\max} \frac{z}{R}$$

$$T = \int \tau dA \cdot z = \int \frac{\tau_{\max}}{R} z^2 dA = \frac{\tau_{\max}}{R} I_p$$

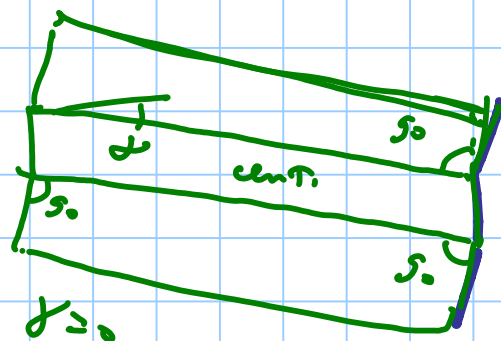
$$J_{xy} = \frac{4}{ab^2}$$

$$a \geq b$$

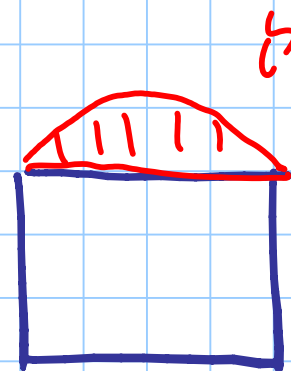
all'alt.



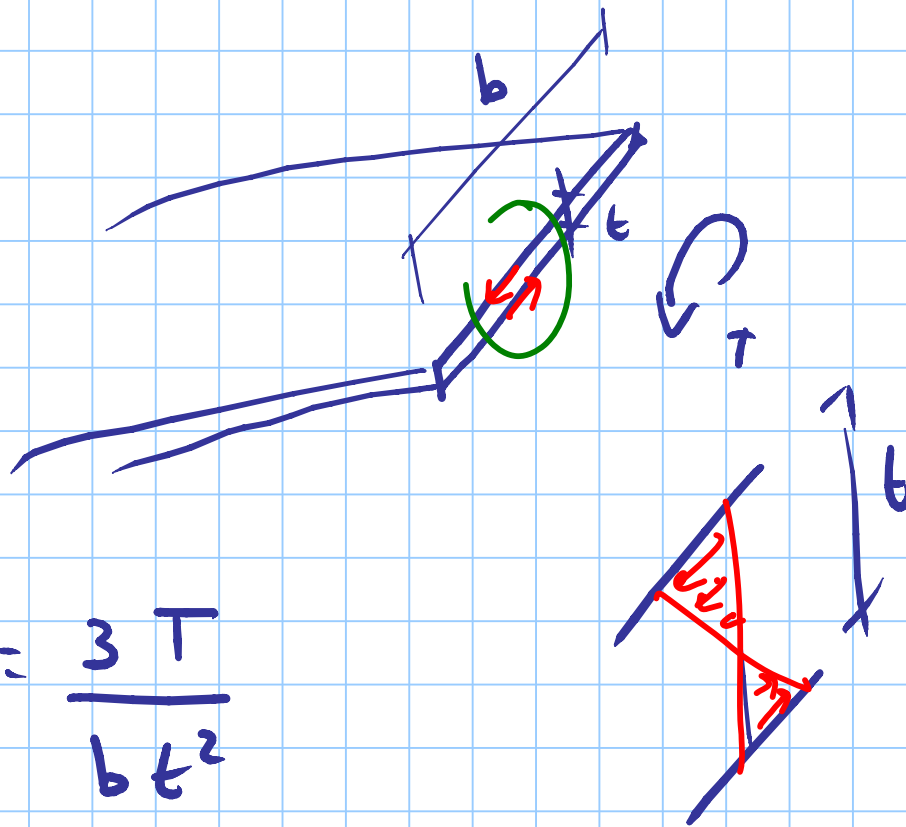
SEZIONE
RETTANGOLARE



spostamenti fuori piano



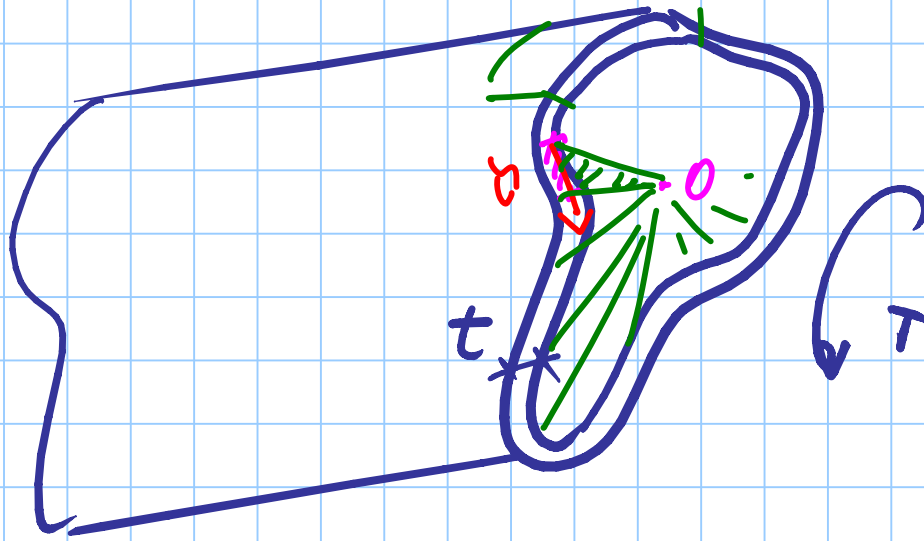
SEZIONE
RETTANGOLARE
SOTTILE



$$\tau = \frac{3T}{bt^2}$$

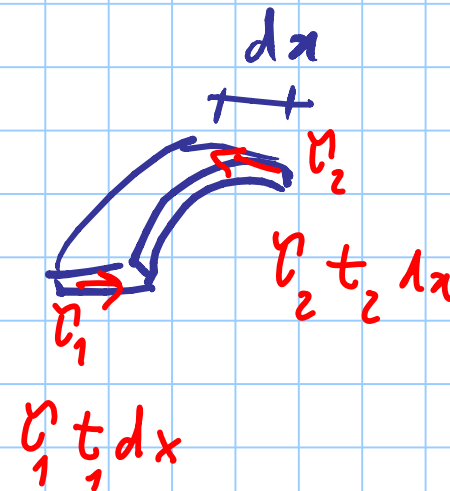
La massima è
fatta da più elementi $\Sigma b \times L$
APERTA

SEZIONE
SOTTILE
CHIUSA

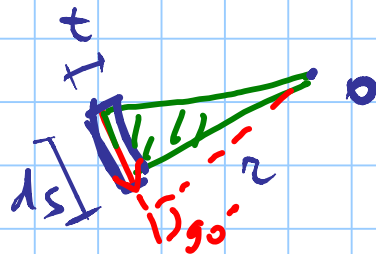


$$\gamma_1 t_1 = \gamma_2 t_2$$

$$\gamma t = \text{const}$$



$$T = \int \underbrace{\gamma t}_{2A} ds$$

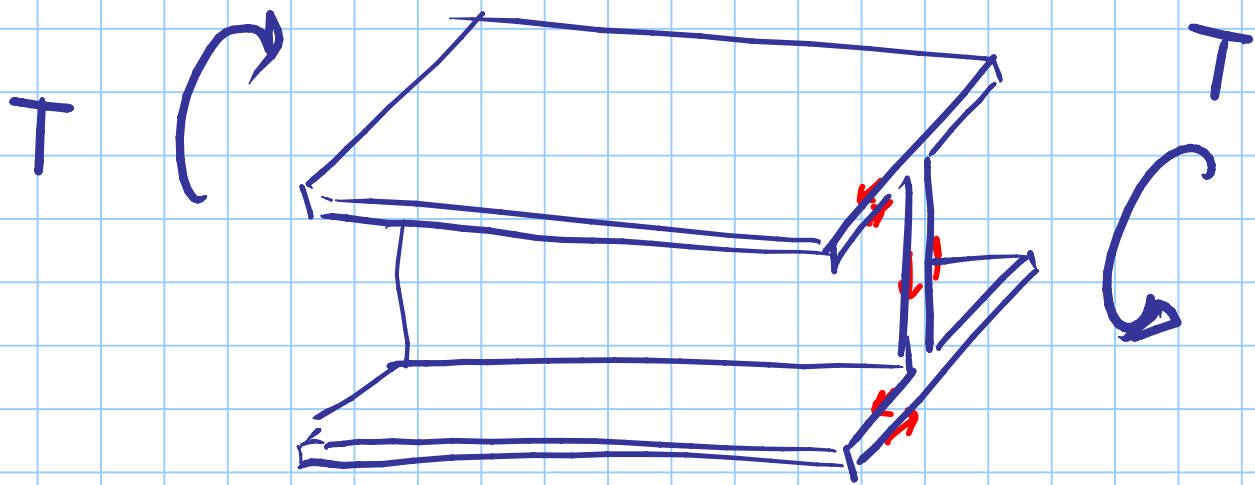


$$\text{Area Triang.} = \frac{\text{base} \times \text{Altezza}}{2} = \frac{ds \cdot r}{2}$$

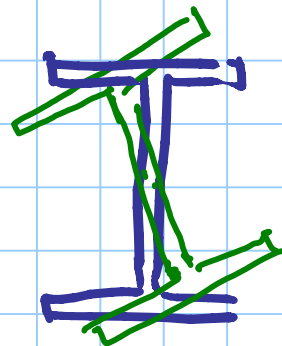
$$T = \sigma_t + 2A_k$$

$$\sigma = \frac{T}{2t + A_k}$$

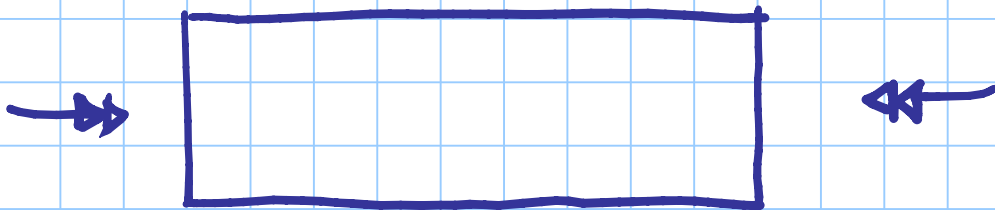
formula di BREDT



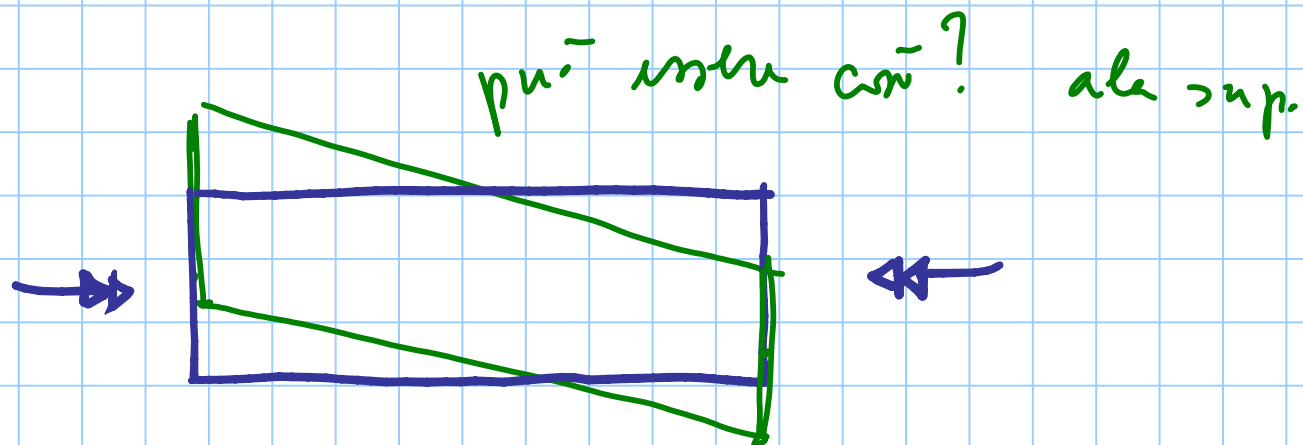
SEZIONE



dall'alto



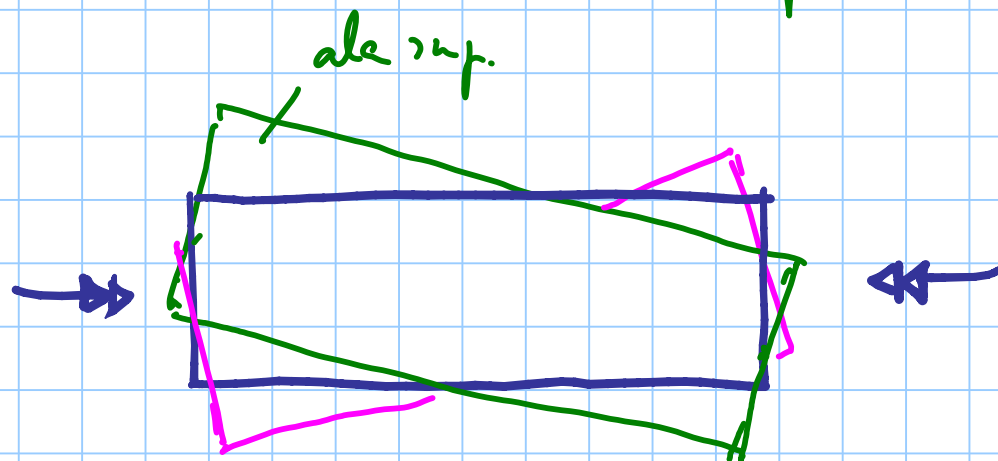
dall'alto



pu' sotto con? ale sup.

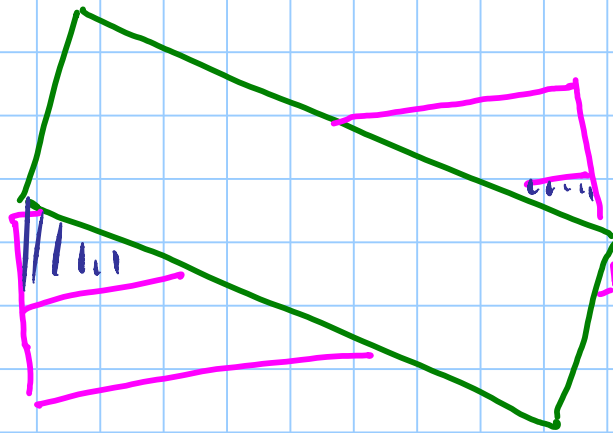
No perché c'è γ

dall'alto



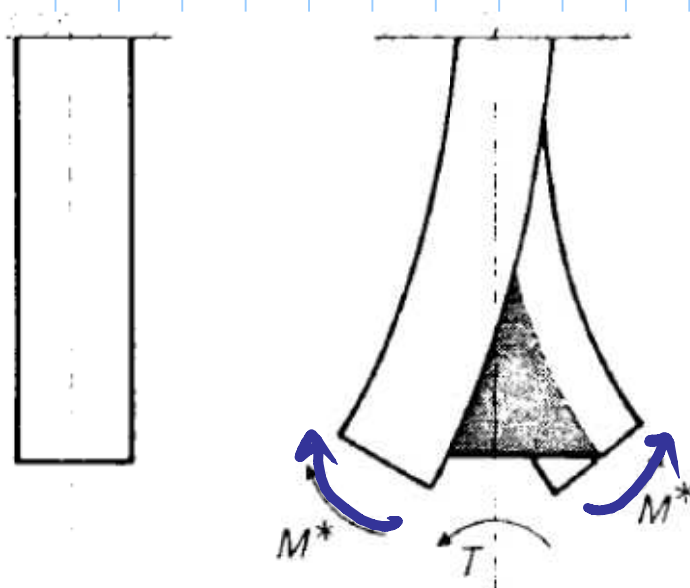
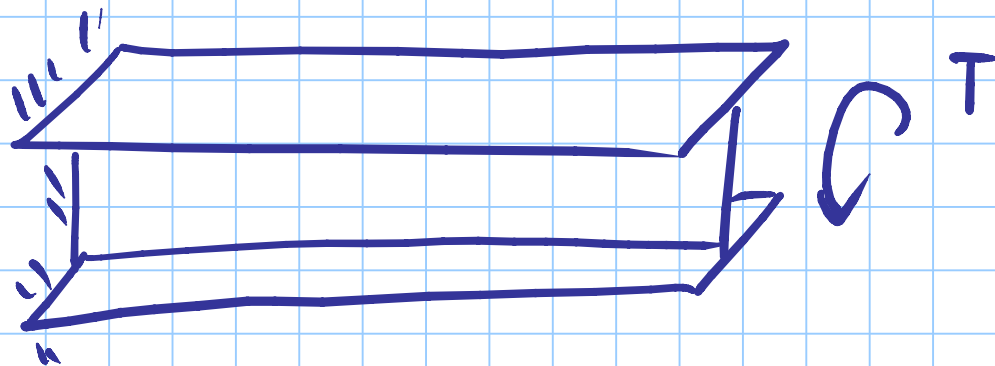
ale sup.

è con perché $\gamma = \rho$
nelle linee mag.



SVERGOLAMENTO

WARPING



la chi è
deformata

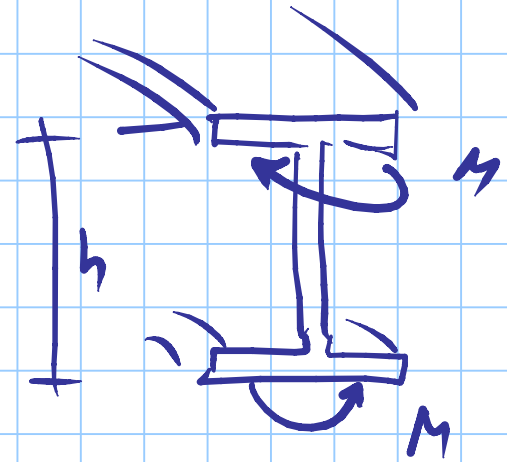
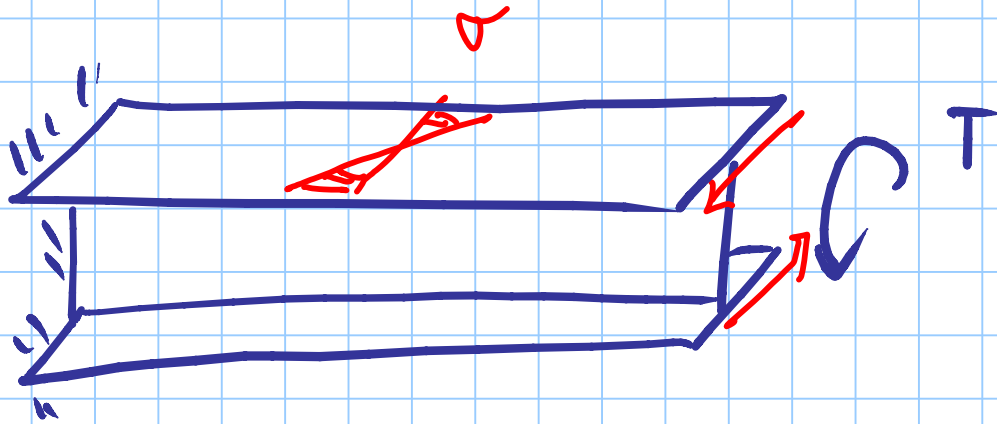
TORSIONE

- PRIMARIA alla De Saint Venant

- SECONDARIA (la sovrapposizione impedita.)

alla Vlasov

teoria delle aree settoriali



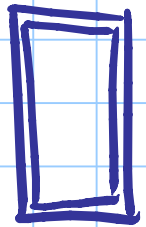
$$\tau = \frac{B}{I_w} w$$

$$B = M h$$

bimoments

RESISTENZA A TORSIONE

PROFILI CHIUSI



$$\tau = \frac{T}{2tA_k} \leq \frac{f_y/\sqrt{3}}{\gamma_m}$$

$$T_{RA} = 2tA_k \frac{f_y/\sqrt{3}}{\gamma_m}$$